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## Regression analysis of longitudinal data with outcome-dependent sampling and informative censoring

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### Abstract

We consider regression analysis of longitudinal data in the presence of outcome-dependent observation times and informative censoring. Existing approaches commonly require correct specification of the joint distribution of the longitudinal measurements, observation time process and informative censoring time under the joint modeling framework, and can be computationally cumbersome due to the complex form of the likelihood function. In view of these issues, we propose a semi-parametric joint regression model and construct a composite likelihood function based on a conditional order statistics argument. As a major feature of our proposed methods, the aforementioned joint distribution is not required to be specified and the random effect in the proposed joint model is treated as a nuisance parameter. Consequently, the derived composite likelihood bypasses the need to integrate over the random effect and offers the advantage of easy computation. We show that the resulting estimators are consistent and asymptotically normal. We use simulation studies to evaluate the finite-sample performance of the proposed method, and apply it to a study of weight loss data that motivated our investigation.

### Keywords

Biased sampling; composite likelihood; informative censoring; joint modeling; time-varying covariate

## 1. INTRODUCTION

In medical follow-up and observational studies, longitudinal data are typically collected together with the duration of the observation window until a terminal event occurs. Two sampling issues commonly arise in analyzing the covariate effect on the longitudinal outcomes: (a) the longitudinal observation times are correlated with the longitudinal outcomes (Robins, 1995; Lipsitz et al., 2002), and (b) the terminal event is associated with the outcomes, which results in informative censoring (Wu and Carroll, 1988; Follmann and Wu, 1995; Little, 1995). Failure to take these biased sampling issues into account may result in misleading analytic results.

Our paper is motivated by a recent study of a web-based weight loss program. Obesity has become a worldwide health issue. In 2010, two-thirds of US adults were estimated to be

obese or overweight (Wang et al., 2011). Among the available weight loss programs, web-based programs have gained popularity because of their flexibility and low cost. It is thus of an increasing need to evaluate the effectiveness of the web-based program on the weight loss over the time. During our motivating web-based weight loss program, a participant was able to voluntarily report his/her weight to the system at each login. A preliminary analysis revealed two interesting facts. First, there was a significant positive association between favorable weight outcomes and higher frequencies of weight entries ( $p$ -value  $< .01$ ). This is not surprising because a participant who is making better progress in losing weight may be more willing to report his/her progress. Second, the length of participation in the program was strongly associated with weight loss. The average weight loss was significantly different between participants who dropped out of the study within 6 months and participants who stayed in the study longer than 6 months (two-sample  $t$  test,  $p$ -value  $< .001$ ). Clearly, these two findings suggest that the self-reported weight data have the aforementioned issues of outcome-dependent sampling and informative censoring. A standard analysis such as generalized estimating equation (GEE) Liang and Zeger (1986) that ignores such biases may conclude that the program appears to be more successful than it actually is.

There is an extensive body of literature in regression analysis with outcome-dependent sampling and informative censoring. When the observation time is outcome-dependent, a common approach is based on likelihoods, where there is a need either to specify the joint distribution of the observation time process and repeated measurements (Liu, 2009; Han et al., 2007; Liang et al., 2009; Song et al., 2009) or to consider marginal or transition models (Lipsitz et al., 2002; Yi et al., 2011). Empirical likelihood approaches have also received success, see Zhou et al. (2002); Chan (2013) for examples. See Ding et al. (2017) for a review of outcome-dependent sampling design for time-to-event outcomes. Alternatively, the estimating equation approach has gained popularity by modeling the marginal mean of the response given covariates (Rotnitzky et al., 1998; Scharfstein et al., 1999; Lin et al., 2004; Sun et al., 2005, 2007). Some authors have also considered the extension to time-varying covariates (Song et al., 2012; Chen et al., 2015). When the censoring is informative, one useful approach is to first build a marginal model for the longitudinal or event variable and then consider a conditional model (Diggle and Kenward, 1994; Little, 1995). Another popular method is joint modeling, in which a shared random effect model is commonly used to characterize the relationship between repeated measurements and a time-to-event process (Self and Pawitan, 1992; Tsiatis et al., 1995; Wulfsohn and Tsiatis, 1997; Wang and Taylor, 2001; Liu and Ying, 2007). This idea has been extended to treat recurrent event time processes as well (Wang et al., 2001); see Tsiatis and Davidian (2004) for an excellent overview.

The main goal of this paper is to provide an alternative to the existing approaches for regression analysis of time-varying covariates in the situation in which the observation and censoring times are correlated with the longitudinal outcomes. The proposed method enjoys two nice properties: (a) it does not require the specification of the observation time process and repeated measurement process; and (b) it bypasses the need to model the random effect distribution and allows for easy computation as no integration over the random effect is needed. The main idea is based on a conditional approach using order statistics and the formulation of a composite likelihood function. Similar ideas have been discussed by several

authors under different settings (Kalbfleisch, 1978; Liang and Qin, 2000; Chen et al., 2015). The inference proceeds by solving the maximization of the composite likelihood function, which is in a much simpler form compared with the functions used in the aforementioned methods (e.g., joint modeling). The resulting estimators are shown to be consistent and asymptotically normally distributed. The rest of this paper is organized as follows. We describe the methodology and present the asymptotic results in Section 2. We report simulation results in Section 3, and discuss an application to the weight loss program data analysis in Section 4. We provide proofs and technical details in the Appendix.

## 2. METHOD

We consider a longitudinal study with  $n$  subjects. For subject  $i$ , let  $Y_i(t)$  be his/her response at time  $t$  and  $\mathbf{X}_i(t)$  be a  $p$ -dimensional vector of time-varying covariates such as the usage of the weight loss program up to time  $t$  in our motivating example. We observe longitudinal outcomes at time points  $t_{i1} < t_{i2} < \dots < t_{iK_i}$  for subject  $i$ , where  $K_i$  is the total number of observations. Define the number of observations of subject  $i$  by  $N_i(t) = \sum_{j=1}^{K_i} \mathbb{1}(t_{ij} \leq t)$  up to time  $t$ , where  $\mathbb{1}$  is the indicator function. The observation times can be viewed as realizations from an underlying counting process  $N_i^*(t)$ , which is censored at the end of follow-up. More specifically, let  $N_i^*(t) = N_i(t \wedge C_i)$ , where  $C_i$  is an informative censoring time, and  $a \wedge b = \min(a, b)$ . The process  $Y_i(t)$  is observed when  $C_i > t$  and  $dN_i(t) = 1$ , in which the derivative is taken with respect to the counting measure. For simplicity, denote  $y_{ij} = Y_i(t_{ij})$ ,  $N_{ij} = N_i(t_{ij})$ , and  $\mathbf{x}_{ij} = \mathbf{X}_i(t_{ij}) = (x_{ij1}, \dots, x_{ijp})^T$  for  $j = 1, \dots, K_i$  and  $i = 1, \dots, n$ .

The parameters of interest are the effects of the time-varying covariates  $\mathbf{X}_i(t)$  on the response variable  $Y_i(t)$ . We extend the semiparametric proportional likelihood ratio model (Luo and Tsai, 2012) to a random effect model by allowing for a subject-specific effect  $\xi_i$ . Specifically, the density of  $Y_{ij}$  given the covariate  $\mathbf{x}_{ij}$  and random effect  $\xi_i$  is

$$f(y_{ij} | \mathbf{x}_{ij}, \xi_i) = \exp(\alpha_{ij} + y_{ij} \mathbf{x}_{ij}^T \boldsymbol{\beta}) f_0(y_{ij} / \xi_i), \quad (2.1)$$

where  $f_0(\cdot)$  is an unspecified baseline density function with covariates  $\mathbf{x}_{ij} = 0$ ,  $\boldsymbol{\beta}$  is the parameter of interest that quantifies the subject-specific effects of the time-varying covariates, and  $\alpha_{ij}$  is the normalizing constant, which is defined as

$$\alpha_{ij} = -\log \int \exp(y \mathbf{x}_{ij}^T \boldsymbol{\beta}) f_0(y / \xi_i) dy.$$

The conditional density of the *observed*  $Y_{ij}$  given  $C_i > t_{ij}$ ,  $dN_{ij}^* = 1$ , covariates  $\mathbf{x}_{ij}$  and the random effect  $\xi_i$  is

$$f\{y_{ij} | dN_{ij}^* = 1, \mathbf{x}_{ij}, \xi_i, C_i > t_{ij}\} = \frac{f(y_{ij} | \mathbf{x}_{ij}, \xi_i) \Pr(dN_{ij}^* = 1 | y_{ij}, \mathbf{x}_{ij}, \xi_i, C_i \geq t_{ij})}{\Pr(dN_{ij}^* = 1, C_i \geq t_{ij} | \mathbf{x}_{ij}, \xi_i)},$$

where the denominator  $\Pr(dN_{ij}^* = 1, C_i \geq t_{ij} | \mathbf{x}_{ij}, \xi_i)$  can be calculated as

$\int f(y | \mathbf{x}_{ij}, \xi_i) \Pr(dN_{ij}^* = 1, C_i \geq t_{ij} | y, \mathbf{x}_{ij}, \xi_i) dy$ . In general, valid inference on the covariate effect  $\beta$  requires correct specification of the joint distribution of the observation time process and informative censoring and  $\Pr(dN_{ij}^* = 1, C_i \geq t_{ij} | y_{ij}, \mathbf{x}_{ij}, \xi_i)$  and the distribution of the random effect  $g(\xi_j)$ . These specifications are subject to potential model misspecification, which may lead to biased inference (Neuhaus et al., 1992).

Here, we propose an alternative method that does not require the specification of the observation time process, the informative censoring and the random effect's distribution. Our strategy is to identify the observed conditional density that is a functional form of the density of interest,  $f_{ij}(y_{ij} | \mathbf{x}_{ij}, \xi_j)$ . The following assumptions are needed.

- (A1) For each subject  $i$ , assume that responses  $y_{i1}, y_{i2}, \dots, y_{iK}$  are independent given their covariates and the unobserved random effect  $\xi_i$ .
- (A2) Conditional on  $X(\cdot)$  and  $\xi$ ,  $C$  is independent of  $(N(\cdot), Y(\cdot))$ .
- (A3) We assume that the probability of observing the response given the response variable, the covariates and the random effect is

$$\Pr(dN_{ij}^* = 1 | y_{ij}, \mathbf{x}_{ij}, \xi_i) = a_1(y_{ij})a_2(\mathbf{x}_{ij})a_3(\xi_i), \quad (2.2)$$

where  $a_1(\cdot)$ ,  $a_2(\cdot)$  and  $a_3(\cdot)$  are completely unspecified nonnegative functions.

Assumption (A1) is standard in the literature. Assumption (A2) is commonly used in the literature to handle informative censoring; see Section 2 of Wang et al. (2001) for an example. Under (A2), the censoring time is allowed to depend on the latent variable, and such a conditional independence assumption substantially relaxes the usual non-informative censoring assumption. Although (A3) specifies a structure through three unspecified functions for the sampling mechanism, it is generally enough to handle the situation with outcome-dependent sampling. For example, when  $a_2(\cdot) = a_3(\cdot) = 1$ , it implies that the probability of observing the response at a particular time point depends on the response only. This is common in practice, e.g., publication bias in meta-analyses, where the probability of a study being published or not depends on the p-value (significant or not) from that study. When  $a_1(\cdot) = a_2(\cdot) = 1$ , it implies that the probability of observing the response at a particular time point depends on the subject-specific random effect only.

Chen et al. (2015) developed a pairwise likelihood to handle outcome-dependent sampling for longitudinal data. The fundamental step in the construction of the pairwise likelihood in Chen et al. (2015) is to consider two observations from a pair of independent subjects. However, the two observations in such a pair are not comparable due to the informative censoring; hence the pairwise likelihood requires proper adjustment. To bypass the challenge of dealing with incomparable pairs, we consider two observations from the same individual: say the  $j$ th and  $k$ th observations of individual  $i$ . Under assumptions (A2) and (A3), the conditional density of observing responses at the  $j$ th and  $k$ th time points for individual  $i$ ,  $(y_{ij}, y_{ik})$ , given their order statistic  $(y^{(1)}, y^{(2)})$ , covariates  $\mathbf{x}_{ij}$  and  $\mathbf{x}_{ik}$ , and random effect  $\xi_i$  is

$$\begin{aligned}
 & f(y_{ij}, y_{ik} | y^{(1)}, y^{(2)}, dN_{ij}^* = 1, dN_{ik}^* = 1, \mathbf{x}_{ij}, \mathbf{x}_{ik}, \xi_i, C_i \geq t_{ij}, C_i \geq t_{ik}) \\
 &= \frac{f(y_{ij}, y_{ik} | dN_{ij}^* = 1, dN_{ik}^* = 1, \mathbf{x}_{ij}, \mathbf{x}_{ik}, \xi_i)}{f(y_{ij} | dN_{ij}^* = 1, dN_{ik}^* = 1, \mathbf{x}_{ij}, \mathbf{x}_{ik}, \xi_i) + f(y_{ik}, y_{ij} | dN_{ij}^* = 1, dN_{ik}^* = 1, \mathbf{x}_{ij}, \mathbf{x}_{ik}, \xi_i)} \\
 &= \frac{f(y_{ij} | dN_{ij}^* = 1, \mathbf{x}_{ij}, \xi_i) f(y_{ik} | dN_{ik}^* = 1, \mathbf{x}_{ik}, \xi_i)}{f(y_{ij} | dN_{ij}^* = 1, \mathbf{x}_{ij}, \xi_i) f(y_{ik} | dN_{ik}^* = 1, \mathbf{x}_{ik}, \xi_i) + f(y_{ij}, y_{ik} | dN_{ij}^* = 1, \mathbf{x}_{ij}, \xi_i) f(y_{ik} | dN_{ik}^* = 1, \mathbf{x}_{ik}, \xi_i)}
 \end{aligned} \tag{2.3}$$

By (A3) and Bayes formula,

$$f(y_{ij} | dN_{ij}^* = 1, \mathbf{x}_{ij}, \xi_i) = \frac{\Pr(dN_{ij}^* = 1 | y_{ij}, \mathbf{x}_{ij}, \xi_i) f(y_{ij} | \mathbf{x}_{ij}, \xi_i)}{\Pr(dN_{ij}^* = 1 | \mathbf{x}_{ij}, \xi_i)} = \frac{a_1(y_{ij}) a_2(\mathbf{x}_{ij}) a_3(\xi_i) f(y_{ij} | \mathbf{x}_{ij}, \xi_i)}{\Pr(dN_{ij}^* = 1 | \mathbf{x}_{ij}, \xi_i)}$$

Hence equation (2.3) can be further simplified by canceling out the common factors  $a_1(\cdot)$ ,  $a_2(\cdot)$ ,  $a_3(\cdot)$  and  $\Pr(dN_{ij}^* = 1 | \mathbf{x}_{ij}, \xi_i)$ ,

$$\begin{aligned}
 & f(y_{ij}, y_{ik} | y^{(1)}, y^{(2)}, dN_{ij}^* = 1, dN_{ik}^* = 1, \mathbf{x}_{ij}, \mathbf{x}_{ik}, \xi_i) \\
 &= \frac{f(y_{ij} | \mathbf{x}_{ij}, \xi_i) f(y_{ik} | \mathbf{x}_{ik}, \xi_i)}{f(y_{ij} | \mathbf{x}_{ij}, \xi_i) f(y_{ik} | \mathbf{x}_{ik}, \xi_i) + f(y_{ij}, y_{ik} | \mathbf{x}_{ij}, \xi_i) f(y_{ik} | \mathbf{x}_{ij}, \xi_i)}.
 \end{aligned} \tag{2.4}$$

Equation (2.4) implies that the conditional density of the observed data (biased sample) given the order statistic is a function of the density functions of the target population. By model (2.1), equation (2.4) becomes

$$\begin{aligned}
 & f(y_{ij}, y_{ik} | y^{(1)}, y^{(2)}, dN_{ij}^* = 1, dN_{ik}^* = 1, \mathbf{x}_{ij}, \mathbf{x}_{ik}, \xi_i) \\
 &= \frac{\exp\{y_{ij} \mathbf{x}_{ij}^T \boldsymbol{\beta} + y_{ik} \mathbf{x}_{ik}^T \boldsymbol{\beta}\}}{\exp\{y_{ij} \mathbf{x}_{ij}^T \boldsymbol{\beta} + y_{ik} \mathbf{x}_{ik}^T \boldsymbol{\beta}\} + \exp\{y_{ij} \mathbf{x}_{ik}^T \boldsymbol{\beta} + y_{ik} \mathbf{x}_{ij}^T \boldsymbol{\beta}\}}.
 \end{aligned} \tag{2.5}$$

The above conditional density does not involve the random effect  $\xi_i$ . Thus, the specification of  $g(\xi_i)$  and integration over the random effect are not required. In addition, both baseline density function  $f_0(\cdot | \xi_i)$  and the normalizing constants ( $a_{ij}$ ,  $a_{ik}$ ) are eliminated by the above conditioning procedure. Therefore, the specification of the baseline density function is not needed either.

Equation (2.5) represents the contribution of one pair of observations ( $j, k$ ) from the  $i$ th individual to the proposed likelihood. We can consider all possible pairs of observations from the same individual and derive their contributions according to equation (2.5). By taking the product of all possible conditional densities while leaving out their correlation, we obtain a composite likelihood function as follows,

$$\begin{aligned}
 L_p(\boldsymbol{\beta}) &= \prod_{i=1}^n \prod_{i < k} \frac{\exp\{y_{ij}\mathbf{x}_{ij}^T\boldsymbol{\beta} + y_{ik}\mathbf{x}_{ik}^T\boldsymbol{\beta}\}}{\exp\{y_{ij}\mathbf{x}_{ij}^T\boldsymbol{\beta} + y_{ik}\mathbf{x}_{ik}^T\boldsymbol{\beta}\} + \exp\{y_{ij}\mathbf{x}_{ik}^T\boldsymbol{\beta} + y_{ik}\mathbf{x}_{ij}^T\boldsymbol{\beta}\}} \\
 &= \prod_{i=1}^n \prod_{j < k} \left[1 + \exp\{-(y_{ij} - y_{ik})(\mathbf{x}_{ij} - \mathbf{x}_{ik})^T\boldsymbol{\beta}\}\right]^{-1}.
 \end{aligned}
 \tag{2.6}$$

We will show that the covariate effects  $\boldsymbol{\beta}$  can be consistently estimated by maximizing  $L_p(\boldsymbol{\beta})$ , or equivalently maximizing the following log-likelihood function in the counting process notation, without estimating the nonparametric component  $f_0(\cdot)$  and specifying the distribution assumption for the unobservable latent variable  $\xi_i$

$$\log L_p(\boldsymbol{\beta}) = \frac{1}{2} \sum_{i=1}^n \int_0^\tau \int_0^\tau \left[-\log\{1 + \exp\{-(Y_i(s) - Y_i(t))(X_i(s) - X_i(t))^T\boldsymbol{\beta}\}\}\right] dN_i(s) dN_i(t).$$

It is worth mentioning that our construction of the likelihood in (2.5) and (2.6) is different from that by Chen et al. (2015). Their paper considered the comparison of outcomes from different individuals,  $Y_{ij}$  and  $Y_{i'j'}$ . In contrast, we are comparing the outcomes from the same individual,  $Y_{ij}$  and  $Y_{ij'}$ , which allows our method to take care of the informative censoring.

By using the asymptotic results of the proposed composite likelihood (Lindsay, 1988; Cox and Reid, 2004), we show in the following statements that the resulting estimating equation produces consistent and asymptotically normally distributed estimators. The proof is provided in the Appendix.

**Theorem 1.** *Under the conditions (a)–(c) listed in the Appendix, the maximizer of  $\log L_p(\boldsymbol{\beta})$ , denoted by  $\hat{\boldsymbol{\beta}}$ , converges to the true  $\boldsymbol{\beta}_0$  with probability tending to one as  $n \rightarrow \infty$ . Moreover,  $\hat{\boldsymbol{\beta}}$  is asymptotically normal with mean  $\boldsymbol{\beta}_0$  and covariance matrix  $V = \boldsymbol{\Sigma}_1^{-1}\boldsymbol{\Sigma}_2\boldsymbol{\Sigma}_1^{-1}$ , where*

$$\boldsymbol{\Sigma}_1 = -E\left\{\frac{\partial^2}{\partial\boldsymbol{\beta}\partial\boldsymbol{\beta}^T}A_i(\boldsymbol{\beta}); \boldsymbol{\beta}_0\right\}, \quad \boldsymbol{\Sigma}_2 = \text{cov}\left\{\frac{\partial}{\partial\boldsymbol{\beta}}A_i(\boldsymbol{\beta}); \boldsymbol{\beta}_0\right\}, \quad \text{and}$$

$$A_i(\boldsymbol{\beta}) = -\sum_{j < k} \log\left[1 + \exp\{-(y_{ij} - y_{ik})(\mathbf{x}_{ij} - \mathbf{x}_{ik})^T\boldsymbol{\beta}\}\right].$$

The covariance matrix  $V$  can be empirically estimated by  $\hat{\boldsymbol{\Sigma}}_1^{-1}\hat{\boldsymbol{\Sigma}}_2\hat{\boldsymbol{\Sigma}}_1^{-1}$ , where

$$\hat{\boldsymbol{\Sigma}}_1 = -\frac{1}{n} \sum_{i=1}^n \left\{ \frac{\partial^2}{\partial\boldsymbol{\beta}\partial\boldsymbol{\beta}^T} A_i(\boldsymbol{\beta}) \Big|_{\boldsymbol{\beta} = \hat{\boldsymbol{\beta}}} \right\}, \quad \text{and} \quad \hat{\boldsymbol{\Sigma}}_2 = \frac{1}{n} \sum_{i=1}^n \left\{ \frac{\partial}{\partial\boldsymbol{\beta}} A_i(\boldsymbol{\beta}) \Big|_{\boldsymbol{\beta} = \hat{\boldsymbol{\beta}}} \right\}^{\otimes 2}.$$

It is worth mentioning that the constructed likelihood function in (2.6) cannot be directly used for estimating the regression effects of constant covariates. The reason is that the

parameter  $\beta$  is associated with the product  $(x_{ij} - x_{ik})^T \beta$ . Suppose the  $l$ -th covariate in  $x$  is a constant, then  $x_{ijl} = x_{ikl}$  for every  $j, k$ , which makes  $\beta_l$  not estimable since the product is always 0. Inference for constant covariate effects may require additional modeling assumption such as the distribution of random effects and the observation time process.

### 3. SIMULATION

We evaluate the numerical performance of the proposed method via simulation studies. We compare the proposed estimator with estimators obtained from three existing methods: the GEE method, joint modeling (JM) of longitudinal outcomes and informative censoring, and the pairwise-likelihood (PL) method (Chen et al., 2015), in which the authors did not consider informative censoring.

We consider a cohort of 200 study subjects and generate three time-varying covariates for each subject,

$$X = (X_1, X_2, X_3)^T, X_1 \sim N(.5 + .5\sqrt{t}, 0.04), X_2 = t, X_3 = t^2, \tag{3.1}$$

where  $t$  is the time after the study enrollment and takes values in a set of grid points  $\{0.1, 0.2, \dots, 9.9, 10\}$ .

In the first scenario, we generate responses  $Y_{ij}$  from a normal distribution, with mean  $X_i^T \beta + \xi_i$  and variance .09, where the true value of  $\beta$  is  $(1, 2, -.1)$ , and  $\xi_i \sim N(0, \sigma_1^2)$  are i.i.d. random effects with two noise levels  $\sigma_1 = .2$  and  $\sigma_1 = .4$ . The probability of observing response  $Y = y_{ij}$  is generated from a logistic model,

$$\text{logit}\{\Pr(dN_{ij} = 1 | y_{ij}; \gamma)\} = \gamma_0 + \gamma_1 y_{ij} + \gamma_2 y_{ij}^2, \tag{3.2}$$

where  $\gamma = (\gamma_0, \gamma_1, \gamma_2)^T$  controls the level of association between the sampling probability and covariates. Specifically, we let  $\gamma$  take three sets of different values that correspond to different levels of association: (1) independence (“indep”), where  $\gamma = (2, 0, 0)^T$ , (2) weak association (“weak”), where  $\gamma = (.1, 2, -.2)^T$ , and (3) strong association (“strong”), where  $\gamma = (-1.5, 4.5, 1)^T$ . The censoring time  $C$  is generated from a normal distribution  $N(7 + 5\xi^2, .5^2)$ .

The GEE and JM methods are implemented in R Console using “geepack” and “JM” packages. We summarize the results based on 1000 replications in Table 1. For each method, we present its estimation bias (Bias), estimated standard error (SE), empirical standard error (SD) and coverage probability (CP %) of the 95% confidence interval. The proposed method provides desired estimation accuracy and yields reasonable CP for the 95% confidence intervals for all simulation settings. Since both the GEE method and PL method ignore the informative censoring, they work poorly under the simulation setting. For example, when  $\sigma_1 = .4$ , the CPs of the PL method range from 0 to 25%, far below the nominal value of 95%. The joint model implemented in the R package can appropriately handle the informative censoring, but cannot deal with the outcome-dependent sampling. When assuming “independent” sampling, JM works well as expected; its CPs are close to 95% and its



standard errors are smaller than those of the proposed method since the distribution information of the informative censoring is used in the likelihood function under the JM. The proposed method shows great advantages when the sampling is outcome-dependent. For example, when  $\sigma_1 = 0.2$  and a “weak” association between the outcome and sampling exists, the proposed method can still provide a small estimation bias, and its CPs for all parameters are greater than 94%. However, the CPs for all other methods are much lower than those obtained from the proposed method, and the bias can be as high as 0.8. When there is “strong” association between the sampling and the outcome, this advantage for the proposed method can be even more obvious.

We also assess the performance of the proposed method with other distributed outcomes such as the exponential distribution. We let  $X_1 \sim N(.5 + .5\sqrt{t}, 0.01)$  and generate  $X_2$  and  $X_3$  in the same way as in the previous simulation. We generate responses  $Y_{ij}$  from an exponential distribution with mean  $(X_i^T \boldsymbol{\beta} + \xi_i)^{-1}$ , where  $\boldsymbol{\beta} = (2, .5, .1)^T$ , and the random effects  $\xi_i$  are generated i.i.d from a uniform distribution on  $(-\sigma_2, \sigma_2)$  with two different noise levels  $\sigma_2 = .1$  and  $.5$ . The probability of observing  $Y$  follows a logistic model as in (3.2), where  $\boldsymbol{\gamma}$  is chosen from three sets of values: (1) independence, where  $\boldsymbol{\gamma} = (2, 0, 0)^T$ , (2) weak association,  $\boldsymbol{\gamma} = (.3, 1, 0)^T$ , and (3) strong association,  $\boldsymbol{\gamma} = (-1, 10, 2)^T$ .

We generate the censoring time from a normal distribution  $C \sim N(8 + 4\xi^2, .4^2)$ . Note that among the four aforementioned methods, only our proposed method and the GEE method do not need to specify the distribution of the longitudinal outcomes. Hence for this scenario, we only evaluate the proposed method and the GEE method on 1000 replicated data sets; the results are listed in Table 2. The 95% confidence intervals produced by the proposed method have coverage probabilities between 93.3% and 95.2%, indicating accurate estimation under all scenarios although the standard error tends to be underestimated. In contrast,  $\hat{\boldsymbol{\beta}}_{GEE}$  has a larger bias, even when  $\boldsymbol{\gamma}$  is independent (e.g., when  $\sigma_2 = .5$ ). When there is a strong association between the sampling and the outcomes, the coverage probability of GEE is always below 40%.

To evaluate the robustness of the proposed method, we conduct sensitivity analysis for which the condition (2.2) in Assumption (A3) is violated. We consider two scenarios for generating the probability of observing response  $Y = y_{ij}$ ,

$$\text{logit}\{\Pr(dN_{ij} = 1 | y_{ij}, \mathbf{x}_{ij})\} = -1 + y_{ij} + x_1(t_j), \tag{3.3}$$

and

$$\text{logit}\{\Pr(dN_{ij} = 1 | y_{ij}, \mathbf{x}_{ij})\} = y_{ij} + .2t_j + x_1(t_j) * y_{ij}/3. \tag{3.4}$$

Those two scenarios can be viewed as moderate derivations from the “weak” dependence situation under (A3). The corresponding results are summarized in “mis-specified 1” and “mis-specified 2” panels in Tables 1 and 2, respectively. It can be seen that the coverage of the regression coefficients are still quite close to the nominal level for most cases, which confirms that the proposed method has some degree of robustness to the violation of (A3).

We also consider a simulation example that compares the performance of our method with that of the partial likelihood (PL) approach (Chen et al. 2015) when the terminal event is non-informative. Here, we generate the data in the same way with the first simulation scenario (linear case), except where the censoring time is generated independently of the random effect following either (i) a “weak” censoring rate from a uniform distribution from 8 to 10 (average censoring rate is 10%) or (ii) a “strong” censoring rate from an exponential distribution  $C = 4.3 + \text{Exp}(1/2)$ , with an average censoring rate of 39%. We summarize the results in Table 3. As expected, both methods manage to estimate the coefficients consistently under all scenarios. PL has better efficiency than our method (SE is smaller by an average of 20%) for most cases, although our method is more computationally efficient (computational complexity is  $O(n^3)$  compared with  $O(n^4)$  for PL).

#### 4. APPLICATION TO WEIGHT LOSS DATA STUDY

We have applied the proposed method to evaluate the effectiveness of the web-based weight control program by using the self reported longitudinal weight data. Web-based programs have become popular among many weight loss programs because of their flexibility and low cost. The effectiveness of such programs has been recently evaluated, and research has shown findings of a positive association between weight loss and the use of web-based programs (Neve et al., 2011). However, most of the published analyses were based on the evaluation of the weight difference, i.e., the difference in a participant’s body weights when entering the study compared to that when leaving the study. Inevitably, ignoring the information of weight and other predictors in the middle of the study will result in misleading interpretations. For example, patients may experience a rebound in weight loss, i.e., lose 10 lbs in the first 3 months and then gain 8 lbs back in the next 2 months. An examination of the overall weight difference will not be able to reveal such patterns. Hence, it is necessary to use weight data over time and study the effect of web-based programs during the entire study period.

The main objective of our study was to conduct regression analysis to evaluate the effect of a web-based weight loss program and weight trend over time after enrollment in the program. We considered data collected from a web-based weight loss program, including records collected in 2008 from 5477 participants. Each participant voluntarily reported his/her weight and the web system also recorded his/her number of logins to the system up to any time  $t$ , which can be used as a measure of the usage of the program up to time  $t$ . The number of self-reported data entries for each participant varied from 2 to 168, with a mean of 6.2. The study duration had a mean of 8.2 months and a maximum of 27.6 months. As expected, we found that the length of enrollment was strongly associated with weight loss. The average weight loss was 3.31 lbs for participants who stayed in the study less than 8 months, and 2.00 lbs for participants who stayed longer than 8 months (two-sample t test,  $p$ -value  $< .001$ ).

We applied the proposed method to the aforementioned data set and considered several time-varying covariates: the number of logins (login), months in the study (month) and its square (month<sup>2</sup>) up to each time of self-report. The estimated coefficients (Est.), associated standard errors (SE) and  $p$ -values are summarized in Table 4. We also present the results

using the method of Chen et al. (2015) and the GEE method. We found that all three covariates had a significant effect on weight. Usage of the web-based program (measured by the number of logins) was positively associated with weight loss. We also found that the enrollment duration had a positive effect (negative sign of month effect) in helping participants lose weight, although there may have been a long-term rebound effect suggested by the positive sign of the month<sup>2</sup> effect. These results confirm the findings of Chen et al. (2015), although our estimated covariate effects were smaller in magnitude than those of the other two methods. This is not surprising: both dependent censoring and biased sampling tend to over-estimate the covariate effects. In contrast, the results obtained using the method of Chen et al. (2015) were based on an independent censoring assumption and the GEE did not account for informative censoring or biased sampling.

We also conducted an analysis for the “active” participants who had at least 10 self-reported records (790 participants). We included an additional covariate called gap, which we defined as the time gap since the last report (equal to 0 if it was the first report). The results, shown in Table 5, demonstrate that the estimates are very close among the “general” and “active” sub-populations (report records 2 and 10). The positive sign of the “gap” confirms the conjecture that the patients who are making progress in weight loss are more likely to report more frequently than those who are not. This justifies the use of the proposed method on this data set because it does not require additional assumptions/modeling on the outcome sampling scheme.

## 5. DISCUSSION

Achieving sufficiently fast computation and avoiding the issue of non-convergence remain challenging problems for the joint modeling approach. In the presence of informative censoring and outcome-dependent observation times, multiple integrations and failure of convergence of the optimization are commonly encountered in practice. Some existing efforts have considered approximation (Sweeting and Thompson, 2011) or Bayesian MCMC methods (Faucett and Thomas, 1996; Brown and Ibrahim, 2003), but they only apply to specific models. In the simulation examples, the implementation of the JM package in R occasionally encountered convergence issues (roughly 2 out of 100 times) when solving the optimization using the quasi-Newton method (“BFGS” option in R). Our method did not experience any convergence issues. The average running time for a single iteration was about 10 seconds for the proposed method, 15 seconds for joint modeling, and 445 seconds for the pairwise likelihood on a cluster machine with Dual 2.2GHz Single Core AMD operation 252 CPUs, 16GB RAM, and 64-bit CentOS Linux System. This is expected since the proposed composite likelihood has a simpler form than the likelihood of joint modeling, and provides a more computationally efficient alternative to the pairwise likelihood. The robustness of the proposed composite likelihood approach due to the requirement of fewer model/distribution assumptions is another advantage.

The idea of conditioning on the order statistics and canceling out the distribution of nuisance variables such as the latent variables has been previously used by Kalbfleisch (1978) for nonparametric testing and by Liang and Qin (2000) for handling missing data under regression analysis. Different from the conditional event used in the literature, we

particularly consider a pair of observations from the same subject to handle the informative censoring issue.

Our work is motivated by evaluating how a web-based weight loss program affects the participant's weight, and the parameter on which we focus is the effect of the time-varying intervention. One limitation of the proposed composite likelihood approach is that the effects of constant covariates are not estimable, and it seems that there is no easy way to extend the current methodology without making additional modeling assumptions on the distribution of the outcomes, random effects, correlation between the informative censoring and the outcome, and the observation time process. Hence, we leave this important topic for future research. The methodology we have developed is applicable to weight loss program studies and other studies that share a similar interest in analyzing the effects of covariates that are changing over the study period. Another challenge of our methodology is the model specification for the likelihood ratio. Note that the nonparametric components such as random effects and the baseline density function of the outcome are not estimated in the proposed estimating procedure. Standard diagnostic tools, such as residual-based methods, are not applicable and cannot handle informative censoring. Developing rigorous test procedures for the modeling assumptions such as a proportional likelihood ratio will be a very interesting and important future research direction. Although the sensitivity analysis suggests some degree of robustness of our method when assumption (A3) is violated, caution should be taken when that assumption is not met. Developing statistical approaches for testing this assumption will be of interest for future research.

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## APPENDIX

### Regularity conditions

We first state a set of regularity conditions needed to establish asymptotic results. For any fixed time point  $t \in [0, \tau]$ , we assume that  $z(t) = \{Y_I(t), X_I(t), N_I(t)\}$ ,  $i = 1, 2, \dots, n$ , are independent, identically distributed with a joint density function  $h\{z(t); \beta\}$ , which satisfies the conditions  $\mathcal{R}$  in Chernoff (1954). The set of conditions is listed as follows.

- a. There exists a neighborhood  $\mathcal{N}_{\beta_0}$  of  $\beta_0$  such that for almost all  $z$  and every  $\beta \in \mathcal{N}_{\beta_0}$ , the following derivatives exist

$$\frac{\partial \log h\{z(t); \beta\}}{\partial \beta}, \frac{\partial^2 \log h\{z(t); \beta\}}{\partial \beta \partial \beta^T}, \frac{\partial^3 \log h\{z(t); \beta\}}{\partial \beta \partial \beta^T \partial \beta}.$$

- b. For any  $\beta \in \mathcal{N}_{\beta_0}$ ,

$$\left| \frac{\partial h\{z(t); \boldsymbol{\beta}\}}{\partial \boldsymbol{\beta}} \right| < H\{z(t)\}, \quad \left| \frac{\partial^2 h\{z(t); \boldsymbol{\beta}\}}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T} \right| < H\{z(t)\}, \quad \left| \frac{\partial^3 h\{z(t); \boldsymbol{\beta}\}}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T \partial \boldsymbol{\beta}} \right| < H\{z(t)\},$$

for some finitely integrable function  $H$  and  $E(H\{z(t)\}) < M$  with  $M$  independent of  $\boldsymbol{\beta}$  and  $t$ .

- c. We assume the matrices  $\boldsymbol{\Sigma}_1$  and  $\boldsymbol{\Sigma}_2$  defined in Theorem 1 to be positive definite and finite.

Assumption (c) is commonly used in the literature, and holds for most situations except some extreme cases. For example, we can show that both  $\boldsymbol{\Sigma}_1$  and  $\boldsymbol{\Sigma}_2$  are always non-negative definite. The positive definiteness assumption only rules out the extreme situation where the likelihood function is flat in  $\boldsymbol{\beta}$  (e.g., the data do not contain adequate information to estimate one of regression coefficients, and further model check is needed to revise the model).

## Proof of Theorem 1

Let  $\boldsymbol{\beta}_0$  be the true value of  $\boldsymbol{\beta}$ . We first show the consistency result. Note that for any  $\delta > 0$ , the intersection of the parameter space of  $\boldsymbol{\beta}$  and the closure of a  $\delta$ -neighborhood of  $\boldsymbol{\beta}_0$  is closed. Therefore  $\log L_p(\boldsymbol{\beta})$  has a local maximum on the intersection. Hence, it suffices to show that the maximum of  $\log L_p(\boldsymbol{\beta})$  has a  $l_2$ -distance less than  $\delta$  from  $\boldsymbol{\beta}_0$ , with the probability going to 1. Consider the Taylor expansion of  $\log L_p(\boldsymbol{\beta})$  around  $\boldsymbol{\beta}_0$ ,

$$\begin{aligned} \frac{1}{n} \{ \log L_p(\boldsymbol{\beta}) - \log L_p(\boldsymbol{\beta}_0) \} &= \frac{1}{n} \frac{\partial L_p(\boldsymbol{\beta}_0)}{\partial \boldsymbol{\beta}} (\boldsymbol{\beta} - \boldsymbol{\beta}_0) \\ &+ \frac{1}{2} \frac{1}{n} (\boldsymbol{\beta} - \boldsymbol{\beta}_0)^T \frac{\partial^2 L_p(\boldsymbol{\beta}_0)}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T} (\boldsymbol{\beta} - \boldsymbol{\beta}_0) + n^{-1} o_p(\|\boldsymbol{\beta} - \boldsymbol{\beta}_0\|_2^2). \end{aligned} \tag{A.1}$$

As  $n \rightarrow \infty$ , since  $\boldsymbol{\beta}_0$  is the unique maximum in its neighborhood, we have

$$\frac{1}{n} \frac{\partial L_p(\boldsymbol{\beta}_0)}{\partial \boldsymbol{\beta}} \rightarrow \mathbf{0}, \quad \frac{1}{n} \frac{\partial^2 L_p(\boldsymbol{\beta}_0)}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T} \rightarrow A,$$

for some negative-definite matrix  $A$ . Note that the first term in (A.1) is  $o_p(1)$ , and the third term is negligible compared to the second term. The second term in (A.1) is negative. Hence  $\log L_p(\boldsymbol{\beta}) < \log L_p(\boldsymbol{\beta}_0)$  with probability 1 for every  $\boldsymbol{\beta}$  that satisfies  $\|\boldsymbol{\beta} - \boldsymbol{\beta}_0\|_2 < \delta$ . The consistency of  $\hat{\boldsymbol{\beta}}$  holds.

Next, we show the  $n^{1/2}$ -consistency of  $\hat{\boldsymbol{\beta}}$ . Using the Taylor expansion and the regularity conditions, we obtain for some  $C_1 > 0$  that,

$$\frac{1}{n} \{ \log L_p(\hat{\boldsymbol{\beta}}) - \log L_p(\boldsymbol{\beta}_0) \} = \frac{1}{n} \frac{\partial \log L_p(\boldsymbol{\beta}_0)}{\partial \boldsymbol{\beta}} (\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}_0) + \frac{1}{2} \frac{1}{n} (\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}_0)^T \frac{\partial^2 \log L_p(\boldsymbol{\beta}_0)}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T} (\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}_0) + C_1 n^{-1} \|\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}_0\|_2^3.$$

Since  $\hat{\beta}$  is consistent for  $\beta_0$ , and  $n^{-1} \frac{\partial^2 \log L_p(\beta_0)}{\partial \beta \partial \beta^T} \xrightarrow{a.s.} -\Sigma_1$  by strong law of large numbers, then for every  $\epsilon > 0$ , there exists a sequence of positive numbers  $c_{n\epsilon} \rightarrow 0$ , such that

$$\|\hat{\beta} - \beta_0\|_2 < c_{n\epsilon} \cdot \left\| \frac{1}{n} \frac{\partial^2 \log L_p(\beta_0)}{\partial \beta \partial \beta^T} + \Sigma_1 \right\|_2 < c_{n\epsilon}.$$

Also, since  $n^{-1} \log L_p(\beta)$  is an empirical average based on i.i.d. observations from each study individual, it is of the order of  $O_p(n^{-1/2})$  at  $\beta_0$ , i.e., there exists  $K_\epsilon > C_1$  such that

$$\left\| \frac{1}{n} \frac{\partial \log L_p(\beta_0)}{\partial \beta} \right\|_2 < n^{-1/2} K_\epsilon.$$

Therefore,

$$0 \leq \frac{1}{n} \{ \log L_p(\hat{\beta}) - \log L_p(\beta_0) \} \leq n^{-1/2} K_\epsilon \|\hat{\beta} - \beta_0\|_2 - \frac{1}{2} (\hat{\beta} - \beta_0)^T \Sigma_1 (\hat{\beta} - \beta_0) + C_1 c_{n\epsilon} \|\hat{\beta} - \beta_0\|_2^2.$$

Since  $\Sigma_1$  is positive definite,  $n^{1/2} \|\hat{\beta} - \beta_0\|_2 = O_p(1)$ . The root-n consistency holds.

For asymptotic normality result, define

$$R_i(s, t; \beta) = \exp\left\{ -(Y_i(s) - Y_i(t))(X_i(s) - X_i(t))^T \beta \right\}.$$

Applying the Taylor expansion of  $\log L_p(\beta) / \beta$  at  $\beta_0$ , we obtain

$$\begin{aligned} 0 &= \sum_{i=1}^n \int_0^\tau \int_0^\tau \left[ -\frac{\partial \log\{1 + R_i(s, t; \hat{\beta})\}}{\partial \beta} \right] dN_i(s) dN_i(t) \\ &= \sum_{i=1}^n \int_0^\tau \int_0^\tau \left[ -\frac{\partial \log\{1 + R_i(s, t; \beta_0)\}}{\partial \beta} \right] dN_i(s) dN_i(t) \\ &\quad + \left( \sum_{i=1}^n \int_0^\tau \int_0^\tau \left[ -\frac{\partial^2 \log\{1 + R_i(s, t; \beta_0)\}}{\partial \beta \partial \beta^T} \right] dN_i(s) dN_i(t) \right)^T (\hat{\beta} - \beta_0) + O_p(n^{-1}), \end{aligned}$$

where the last term  $O_p(n^{-1})$  is due to the fact that  $\|\hat{\beta} - \beta_0\|_2^2 = O_p(n^{-1})$ . Therefore, we can multiply both sides by  $n^{1/2}$ , and obtain

$$n^{1/2}(\hat{\beta} - \beta_0) = A_n^{-1} n^{1/2} B_n + O_p(n^{-1/2}),$$

where

$$\mathbf{A}_n = -\frac{1}{n} \sum_{i=1}^n \int_0^\tau \int_0^\tau \left[ -\frac{\partial^2 \log\{1 + R_i(s, t; \boldsymbol{\beta}_0)\}}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T} \right] dN_i(s) dN_i(t),$$

$$\mathbf{B}_n = \frac{1}{n} \sum_{i=1}^n \int_0^\tau \int_0^\tau \left[ -\frac{\partial \log\{1 + R_i(s, t; \boldsymbol{\beta}_0)\}}{\partial \boldsymbol{\beta}} \right] dN_i(s) dN_i(t).$$

Since  $\mathbf{A}_n$  and  $\mathbf{B}_n$  are both empirical average of functionals based on i.i.d. observations, we have  $\mathbf{A}_n \xrightarrow{p} \boldsymbol{\Sigma}_1$  and  $n^{1/2} \mathbf{B}_n \xrightarrow{d} N(\mathbf{0}, \boldsymbol{\Sigma}_2)$  as  $n \rightarrow \infty$  by the law of large numbers and the CLT. This completes the proof.

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**Table 1:**

Simulation scenario 1, comparing the performance of the proposed estimator  $\hat{\beta}$  with those of the GEE ( $\hat{\beta}_{GEE}$ ), joint modeling ( $\hat{\beta}_{JM}$ ) and pairwise-likelihood ( $\hat{\beta}_{PL}$ ) estimators

$\sigma_1$	$\gamma$	$\beta$			$\hat{\beta}_{GEE}$			$\hat{\beta}_{JM}$			$\hat{\beta}_{PL}$							
		Bias	SE	SD	CP	Bias	SE	SD	CP	Bias	SE	SD	CP	Bias	SE	SD	CP	
0.2	‘indep’	$\beta_1$	.012	.191	.197	93.2	-.054	.202	.208	93.8	-.002	.144	.146	94.4	-.323	.152	.157	42.8
		$\beta_2$	-.001	.099	.099	94.7	.011	.121	.128	94.1	-.009	.080	.082	94.3	-.572	.095	.099	0
		$\beta_3$	.000	.012	.012	94.8	-.010	.016	.017	89.5	.001	.009	.010	94.3	.018	.012	.013	63.6
	‘‘weak’’	$\beta_1$	.014	.216	.220	94.1	.875	.198	.202	1.0	.373	.151	.153	31.5	-.320	.171	.175	52.3
		$\beta_2$	-.002	.114	.112	94.7	-.193	.126	.131	64.7	-.152	.086	.087	58.6	-.578	.108	.113	.5
		$\beta_3$	.000	.013	.013	94.0	-.009	.016	.017	89.0	.004	.010	.010	93.1	.019	.013	.014	67.0
	‘‘strong’’	$\beta_1$	.013	.237	.237	94.0	2.23	.187	.193	0.0	.958	.159	.157	0.0	-.327	.192	.192	59.5
		$\beta_2$	.002	.131	.128	95.3	-.512	.122	.128	1.5	-.434	.085	.085	0.0	-.589	.127	.129	.7
		$\beta_3$	.000	.014	.015	94.8	-.013	.015	.016	82.1	.010	.010	.010	80.4	.021	.015	.016	68.4
‘‘mis-specified 1’’	$\beta_1$	-.165	.217	.218	88.1	.435	.209	.214	43.2	.133	.156	.155	87.0	-.508	.170	.167	16.3	
	$\beta_2$	-.013	.115	.112	95.3	-.048	.133	.141	91.5	-.059	.090	.090	90.0	-.577	.109	.114	.3	
	$\beta_3$	.001	.013	.013	95.5	-.017	.017	.019	81.5	-.001	.010	.010	94.9	.019	.014	.015	67.5	
‘‘mis-specified 2’’	$\beta_1$	.037	.206	.211	93.8	.628	.203	.210	14.0	.292	.150	.154	51.8	-.300	.163	.163	54.7	
	$\beta_2$	-.060	.110	.109	90.5	-.149	.128	.136	77.1	-.133	.086	.087	65.5	-.623	.106	.111	.1	
	$\beta_3$	.003	.012	.012	93.6	-.011	.017	.018	88.5	.003	.010	.010	93.1	.02	.013	.014	63.2	
0.4	‘‘indep’’	$\beta_1$	.012	.189	.198	93.7	-.450	.382	.390	75.7	.004	.161	.164	93.8	-.693	.107	.110	0
		$\beta_2$	-.001	.089	.090	94.9	.289	.207	.217	65.1	-.010	.071	.072	94.7	-1.129	.084	.084	0
		$\beta_3$	.000	.009	.009	94.5	-.073	.028	.030	29.0	.001	.007	.008	95.2	.031	.009	.010	8.4
‘‘weak’’	$\beta_1$	.012	.216	.226	93.8	1.341	.365	.370	2.8	.153	.171	.177	84.9	-.694	.125	.131	0	

$\sigma_1$	$\gamma$	$\beta$	$\hat{\beta}$			$\hat{\beta}_{GEE}$			$\hat{\beta}_{JM}$			$\hat{\beta}_{PL}$						
			Bias	SE	SD	CP	Bias	SE	SD	CP	Bias	SE	SD	CP	Bias	SE	SD	CP
		$\beta_2$	-.002	.105	.106	95.1	-.172	.224	.232	90.3	-.144	.078	.078	55.2	-1.145	.101	.103	0
		$\beta_3$	.000	.011	.011	93.8	-.053	.030	.032	52.3	.006	.008	.008	88.5	.033	.012	.012	18.1
		$\beta_1$	-.003	.240	.239	94.8	3.39	.350	.349	0.0	.401	.171	.168	34.8	-.685	.148	.150	.1
		$\beta_2$	.001	.121	.123	94.6	-.732	.223	.233	4.8	-.401	.079	.079	0.0	-1.191	.127	.138	0
		$\beta_3$	.000	.012	.013	94.5	-.033	.028	.031	67.3	.017	.008	.008	48.8	.039	.014	.016	24.5
		$\beta_1$	-.166	.215	.218	87.5	.481	.386	.396	79.0	.034	.175	.182	92.9	-.875	.121	.121	0
		$\beta_2$	-.009	.103	.102	95.3	.141	.232	.240	85.1	-.075	.082	.143	81.2	-1.13	.097	.099	0
		$\beta_3$	.001	.010	.011	94.8	-.076	.030	.032	34.3	.002	.009	.010	94.5	.031	.011	.011	18.3
		$\beta_1$	.040	.204	.209	93.3	.818	.374	.379	40.1	.209	.167	.235	71.2	-.659	.116	.119	0
		$\beta_2$	-.051	.098	.098	91.5	-.016	.224	.231	92.9	-.133	.077	.139	60.7	-1.17	.097	.099	0
		$\beta_3$	.001	.010	.010	93.7	-.070	.029	.031	36.5	.003	.008	.010	87.4	.032	.011	.011	17.5

**Table 2:**

Simulation scenario 2, comparing the performance of the proposed estimator  $\hat{\beta}$  with that of the GEE ( $\hat{\beta}_{GEE}$ ).

random effect	$\gamma$	$\beta$	$\hat{\beta}$				$\hat{\beta}_{GEE}$			
			Bias	SE	SD	CP	Bias	SE	SD	CP
low $\sigma_2 = .1$	"indep" (2, 0, 0)	$\beta_1$	.001	.431	.445	93.7	-.003	.085	.084	95.9
		$\beta_2$	.001	.146	.146	94.0	.001	.084	.082	96.0
		$\beta_3$	.000	.015	.015	95.0	.000	.012	.012	95.0
	"weak" (.3, 1, 0)	$\beta_1$	.007	.460	.484	93.6	-.259	.084	.085	14.7
		$\beta_2$	.003	.159	.162	94.6	-.001	.087	.088	94.0
		$\beta_3$	.000	.017	.017	94.9	.002	.013	.013	93.8
	"strong" (-1, 10, 2)	$\beta_1$	-.011	.432	.427	95.2	-.212	.066	.066	11.6
		$\beta_2$	.006	.151	.151	94.7	-.261	.065	.065	1.8
		$\beta_3$	.000	.017	.017	93.8	-.023	.010	.010	33.8
"mis-specified 1" (-1, 10, 2)	$\beta_1$	.083	.453	.470	93.6	-.234	.082	.082	20.5	
	$\beta_2$	.006	.154	.153	94.9	.023	.084	.083	94.0	
	$\beta_3$	.000	.016	.016	95.3	.001	.012	.012	94.3	
"mis-specified 2" (-1, 10, 2)	$\beta_1$	-.095	.499	.513	93.0	-.224	.093	.092	32.4	
	$\beta_2$	.027	.166	.167	94.8	.034	.090	.089	94.2	
	$\beta_3$	.000	.017	.017	95.2	.001	.013	.012	95.2	
high $\sigma_2 = .5$	"indep" (2, 0, 0)	$\beta_1$	.004	.42.6	.43.7	94.0	-.087	.088	.087	83.8
		$\beta_2$	.002	.142	.142	94.7	.042	.082	.080	92.0
		$\beta_3$	.000	.014	.015	94.8	-.003	.011	.011	93.6
	"weak" (.3, 1, 0)	$\beta_1$	.004	.451	.471	93.3	-.349	.086	.086	3.3
		$\beta_2$	.005	.153	.155	94.7	.044	.084	.085	91.5
		$\beta_3$	-.001	.016	.016	94.6	-.002	.012	.012	93.0
	"strong" (-1, 10, 2)	$\beta_1$	-.008	.423	.416	95.0	-.283	.069	.069	2.7
		$\beta_2$	.005	.145	.146	94.9	-.229	.064	.064	5.3
		$\beta_3$	.000	.016	.016	94.2	-.025	.009	.009	22.2
"mis-specified 1" (-1, 10, 2)	$\beta_1$	.121	.446	.439	94.9	-.318	.085	.084	4.2	
	$\beta_2$	-.006	.149	.143	96.2	.063	.081	.081	86.9	
	$\beta_3$	.000	.015	.015	95.5	-.003	.011	.011	94.1	
"mis-specified 2" (-1, 10, 2)	$\beta_1$	-.06	.494	.485	94.3	-.314	.095	.094	10.8	
	$\beta_2$	.020	.162	.156	95.6	.079	.087	.087	85.1	
	$\beta_3$	.000	.016	.016	95.7	-.003	.012	.012	94.2	

**Table 3:**

Simulation scenario 3, comparing the performance of the proposed estimator  $\hat{\beta}$  with those of the pairwise-likelihood ( $\hat{\beta}_{PL}$ ) estimators under non-informative censoring.

censor	$\sigma_1$	$\gamma$	$\beta$	$\hat{\beta}$				$\hat{\beta}_{PL}$			
				Bias	SE	SD	CP	Bias	SE	SD	CP
"weak"	0.2	"indep"	$\beta_1$	.004	.214	.216	94.9	.03	.168	.180	92.4
			$\beta_2$	.002	.096	.099	94.6	.020	.095	.101	93.2
			$\beta_3$	.000	.009	.009	94.1	-.002	.008	.009	92.3
	"weak"	$\beta_1$	.003	.238	.238	95.0	.033	.187	.196	93.3	
		$\beta_2$	.002	.109	.111	94.9	.015	.103	.109	93.1	
		$\beta_3$	.000	.010	.010	94.6	-.002	.009	.009	92.2	
	"strong"	$\beta_1$	.008	.256	.256	94.0	.035	.206	.209	95.3	
		$\beta_2$	-.001	.121	.124	93.7	.006	.114	.119	93.5	
		$\beta_3$	.000	.011	.011	93.8	-.001	.010	.011	92.4	
0.4	"indep"	$\beta_1$	.002	.214	.217	95.0	.044	.123	.133	91.4	
		$\beta_2$	.001	.096	.099	94.2	-.006	.084	.091	91.9	
		$\beta_3$	.000	.009	.009	94.8	-.002	.007	.008	91.8	
	"weak"	$\beta_1$	.003	.244	.243	94.5	.044	.145	.151	93.0	
		$\beta_2$	.000	.112	.114	94.8	-.019	.095	.101	92.9	
		$\beta_3$	.000	.010	.010	94.3	-.001	.008	.009	92.6	
	"strong"	$\beta_1$	.004	.265	.260	94.6	.051	.168	.172	93.5	
		$\beta_2$	.006	.125	.127	94.0	-.041	.114	.121	91.5	
		$\beta_3$	-.001	.011	.011	93.5	.000	.010	.011	94.4	
"strong"	0.2	"indep"	$\beta_1$	-.011	.243	.251	93.6	.035	.191	.192	94.7
			$\beta_2$	.006	.113	.118	93.3	.014	.114	.122	92.4
			$\beta_3$	.000	.012	.014	91.2	-.001	.014	.016	92.1
	"weak"	$\beta_1$	-.005	.278	.289	93.6	.035	.218	.211	95.0	
		$\beta_2$	.007	.128	.134	93.5	.012	.125	.131	93.9	
		$\beta_3$	.000	.014	.015	90.8	-.001	.015	.016	91.4	
	"strong"	$\beta_1$	-.007	.313	.313	95.5	.027	.249	.243	94.7	
		$\beta_2$	.005	.145	.156	91.8	.005	.141	.148	93.4	
		$\beta_3$	.000	.015	.017	89.4	-.000	.017	.018	92.0	
0.4	"indep"	$\beta_1$	-.012	.244	.252	94.7	.047	.139	.142	92.7	
		$\beta_2$	.007	.113	.118	93.0	-.020	.102	.110	92.0	

censor	$\sigma_1$	$\gamma$	$\beta$	$\hat{\beta}$				$\hat{\beta}_{PL}$			
				Bias	SE	SD	CP	Bias	SE	SD	CP
			$\beta_3$	.000	.012	.013	91.7	.001	.013	.015	90.1
		“weak”	$\beta_1$	-.010	.285	.287	95.3	.044	.167	.167	93.9
			$\beta_2$	.008	.132	.136	93.2	-.027	.115	.123	91.6
			$\beta_3$	.000	.014	.015	91.4	.001	.015	.016	91.5
		“strong”	$\beta_1$	.003	.265	.262	94.5	.056	.201	.204	93.3
			$\beta_2$	.004	.125	.141	93.9	-.041	.140	.151	90.9
			$\beta_3$	-.001	.011	.012	93.5	.000	.017	.019	91.3

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**Table 4:**

Weight loss data analysis using the proposed method, the method of Chen et al. (2015) and the GEE.

Covariate	Proposed			Chen et al. (2015)			GEE		
	Est	SE	p-value	Est	SE	p-value	Est	SE	p-value
Login	-.010	.003	< .001	-.049	.007	< .001	-.044	.002	< .001
Month	-.190	.061	.002	-.261	.247	.292	-.472	.063	< .001
Month <sup>2</sup>	.008	.002	< .001	.025	.009	.005	.025	.002	< .001

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**Table 5:**

Weight loss data analysis using the proposed method

Covariate	Report records 2			Report records 10		
	Est	SE	p-value	Est	SE	p-value
Login	-.008	.003	.003	-.008	.003	.003
Month	-.252	.066	< .001	-.246	.068	< .001
Month <sup>2</sup>	.009	.002	< .001	.009	.002	< .001
Gap	.180	.026	< .001	.215	.031	< .001

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